



# Sparse Representation Classifier

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#### Laboratoire d'InfoRmatique en Image et Systèmes d'information

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# Outline

Formulation
Robust Recognition
Experiments



## **FORMULATION** *Face recognition as sparse representation*

**Assumption:** the test image,  $y \in \mathbb{R}^D$ ,  $D = w \times h$ , can be expressed as a linear combination of k training images, say  $\{y_i^1, \dots, y_i^k\}$  of the same subject:  $y = y_i^1 \alpha_1 + y_i^2 \alpha_2 + \dots + y_i^k \alpha_k \doteq A_i \vec{\beta}_i, \quad \vec{\beta}_i \in \mathbb{R}^k$  $y = A_1 \vec{\beta}_1 + A_2 \vec{\beta}_2 + \dots + A_n \vec{\beta}_n = Ax$ 



The solution,  $x \in \mathbb{R}^N$ ,  $N = n \times k$ , should be a sparse vector —  $\frac{n-1}{n}$  of its entries should be zero, except for the ones associated with the correct subject.

## **ROBUST RECOGNITION** *Occlusion + varying illumination*







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## **ROBUST RECOGNITION** *Occlusion and Corruption*







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## **ROBUST RECOGNITION** *Tackling Corruption and Occlusion*

Properties that help to tackle occlusion:

- Redundancy (essential for error-correcting code)
  - But nothing is more redundant than the original images
- Locality (using local features and parts such as ICA and LNMF)

But no features or parts are more local than the original pixels

Sparsity (error incurred by occlusion is typically sparse)
But sparse representation not been thoroughly exploited in recognition

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ICA : Independent component analysis LNMF : Local Non-negative Matrix Factorization

## **ROBUST RECOGNITION Properties of the Occlusion**



y = Ax + e

 $y_0 = Ax$ 

e

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Several characteristics of occlusion

- Randomly supported errors (location is unknown) and unpredictable)
- Gross errors (arbitrarily large in magnitude)
- Sparse errors? (concentrated on relatively small part(s) of the image)

### **ROBUST RECOGNITION** *Problem Formulation*

Problem: Find the correct (sparse) solution x from the corrupted and overdetermined ( $D \gg N$ ) system of linear equations:

$$y = Ax + e, \quad A \in \mathbb{R}^{D \times N}, \ y, e \in \mathbb{R}^{D}.$$

Conventionally, the minimum 2-norm (least squares) solution is used:







## ROBUST RECOGNITION Joint Sparsity

$$y = Ax + e \iff y = [A \ I] \begin{bmatrix} x \\ e \end{bmatrix} \doteq Bq, \quad B \in \mathbb{R}^{D \times (D+N)}.$$

Thus, we are looking for a sparse solution q to an under-determined (D < D + N) system of linear equations y = Bq:

$$\begin{array}{lll} (P_0) & \widehat{q}_0 \ = \ \arg\min_q \ \|q\|_0 & \text{s.t.} & y = Bq. \\ & & & \\ & & \\ (P_1) & & & \\ \widehat{q}_1 \ = \ \arg\min_q \ \|q\|_1 & \text{s.t.} & y = Bq. \end{array}$$

The problem  $(P_1)$  can be solved efficiently via Linear Programming, and the solution is stable under moderate noise [Candes & Tao'04, Donoho'04].

The equivalence holds iff  $||q||_0 = ||x||_0 + ||e||_0 \le \mathsf{EBP}(B)$ .

## ROBUST RECOGNITION L<sub>1</sub> versus L<sub>2</sub> Solution



## **ROBUST RECOGNITION** *Classification from Coefficients*



Classification criterion: assign to the class with the smallest residual.

### **ROBUST RECOGNITION** *Algorithm Summary*

**Input:**  $N = n \times k$  training images of size  $D = w \times h$  pixels, partitioned into n classes,  $A_1, \ldots, A_n$ , and an (occluded) test sample y.

Set  $B = [A_1, A_2, \dots, A_n, I] \in \mathbb{R}^{D \times (D+N)}$ . Solve the linear programming problem:

$$\widehat{q}_1 = rgmin_{q=[x\,e]} \|q\|_1$$
 s.t.  $y = Bq$ 

for i = 1: n

Compute the reconstruction  $\hat{y}_0 = y - \hat{e}_1$ .

Compute the residual  $r_i = \|\hat{y}_0 - A\delta_i(\hat{x}_1)\|_2$ . end

**Output:**  $id(y) = arg \min_{i=1,...,n} r_i$ 

## **EXPERIMENTS** *Varying Level of Random Corruption*

Extended Yale B Database (38 subjects)

Training: subsets 1 and 2 (717 images) Testing: subset 3 (453 images)



## **EXPERIMENTS** *Varying Levels of Contiguous Occlusion*

Extended Yale B Database (38 subjects)

Error Back Projection ~ 13.3%.  $\widehat{y}_0$  $\widehat{e}_1$  $\widehat{x}_1$  $\boldsymbol{y}$ Testing: subset 3 (453 images) 100 98.5% 90 90.3% 80 2 Recognition rate 70 65.3% 60 Algorithm 1 PCA + NN 50 ICA I + NN NMF + NN 40 30 0 5 10 15 20 25 30 35 40 45 50 Percent occluded (%) 14

Training: subsets 1 and 2 (717 images),

## **EXPERIMENTS** *Recognition with Face Parts Occluded*



Occluded	Rec. rate
Nose	98.7%
Mouth	97.1%
Eyes	95.6%

Results corroborate findings in human vision: the eyebrow or eye region is most informative for recognition [Sinha'06].

However, the difference is less significant for our algorithm than for humans.

## **EXPERIMENTS** *Recognition with Disguises*

The AR Database (100 subjects) Training: 799 images (un-occluded) Error Back Projection = 11.6%. Testing: 200 images (with glasses) 200 images (with scarf)



Cases	Rec. rate	Cases	Rec. rate
Sunglasses	97.5%	Scarves	93.5%
Men	97.5%	Women	93.5%
Men, sunglasses	100%	Women, sunglasses	95.0%
Men, scarves	95.0%	Women, scarves	92.0%