

Traitement et Analyse des données visuelles et sonores

Méthodes avancées en image et vidéo

Ecole Centrale de Lyon

Laboratoire d'InfoRmatique en Image et Systèmes d'information

LIRIS UMR 5205 CNRS/INSA de Lyon/Université Claude Bernard Lyon 1/Université Lumière Lyon 2/Ecole Centrale de Lyon

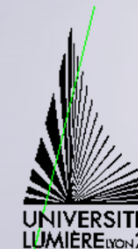
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Summary

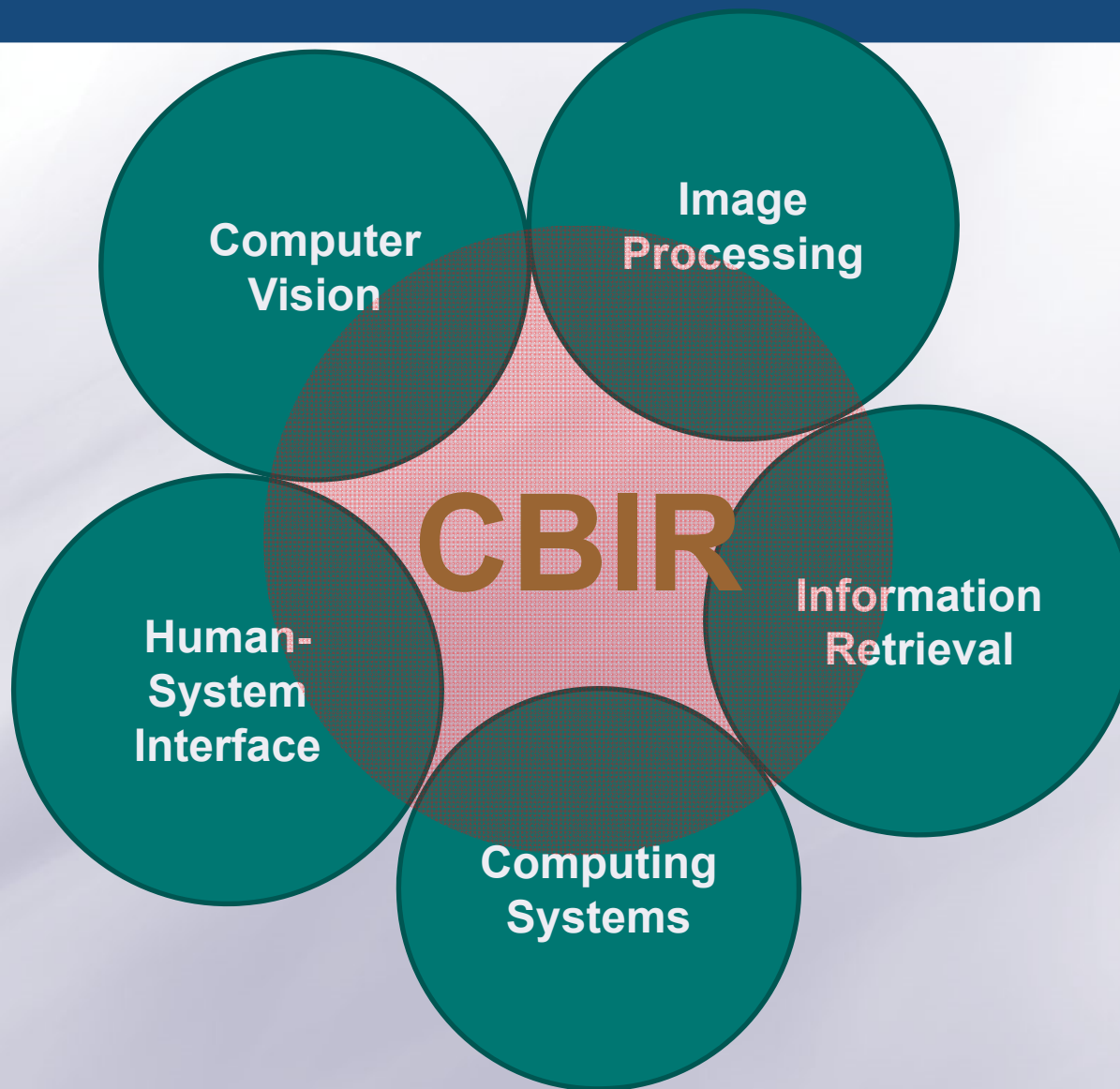
- Content Based Image Retrieval
- Image Processing: Super-Resolution
- Acquisition/Modelling: Range Face Acquisition
- Image Analysis: applied to Face Recognition
- Audio as a Modality

CBIR - content-based image retrieval

- ☰ [Kato 92] experiments into automatic retrieval of images from a database by colour and shape feature
- ☰ And later to describe the process of retrieving desired images from a large collection on the basis of
 - Features (primitive or semantic such as colour, texture and shape)
 - Automatically extracted from the images themselves
 - Retrieval of images by manually-assigned keywords is definitely not CBIR as the term is generally understood – even if the keywords describe image content

CBIR - content-based image retrieval

- ≡ Image databases are essentially unstructured: digitized images consist purely of arrays of pixel intensities, with no inherent meaning
- ≡ Need to extract useful information from the raw data before any kind of reasoning about the image's contents is possible
 - such as recognizing the presence of particular shapes or textures
- ≡ Raw material, words stored as ASCII character strings, has already been logically structured by the author [Santini and Jain, 1997]
- ≡ There is no equivalent of level 1, basic level (pixels), retrieval in a text database
- ≡ Big Data



CBIR vs Images Processing & Computer Vision

- CBIR draws its methods from image processing, computer vision to achieve image retrieval in big size data
- Image processing covers also enhancement, compression, transmission, and interpretation
- Grey areas such as object recognition by feature analysis
- Usually fairly clear-cut distinction between image analysis and CBIR

Police forces use automatic face recognition systems in one of two ways: Firstly, the image in front of the camera may be compared with a single individual's database record to verify his or her identity. In this case, only two images are matched, a process few observers would call CBIR. Secondly, the entire database may be searched to find the most closely matching images. This is a genuine example of CBIR.

Image Retrieval

Research and development issues in CBIR shared with image processing and information retrieval:

- Understanding image users' needs and information-seeking behaviour
- Identification of suitable ways of describing image content
- Extracting such features from raw images
- Providing compact storage for large image databases
- Matching query and stored images in a way that reflects human similarity judgements
- Efficiently accessing stored images by content
- Providing usable human interfaces to CBIR systems

Video Retrieval

Key research issues in video retrieval include:

- automatic shot and scene detection
- ways of combining video, text and sound for retrieval
- effective presentation of search output for the user

CBIR - Content Based Image Retrieval

- Feature Extraction
 - Global Features
 - Local Features
- Search and Retrieval
 - Similarity measures
 - Region-based approaches
 - Classification / Clustering
- Annotation
 - Classification Models
 - Joint models
- Relevance Feedback and Learning
- Multimodal Fusion and Retrieval
- Hardware Support
- Interface and visualization

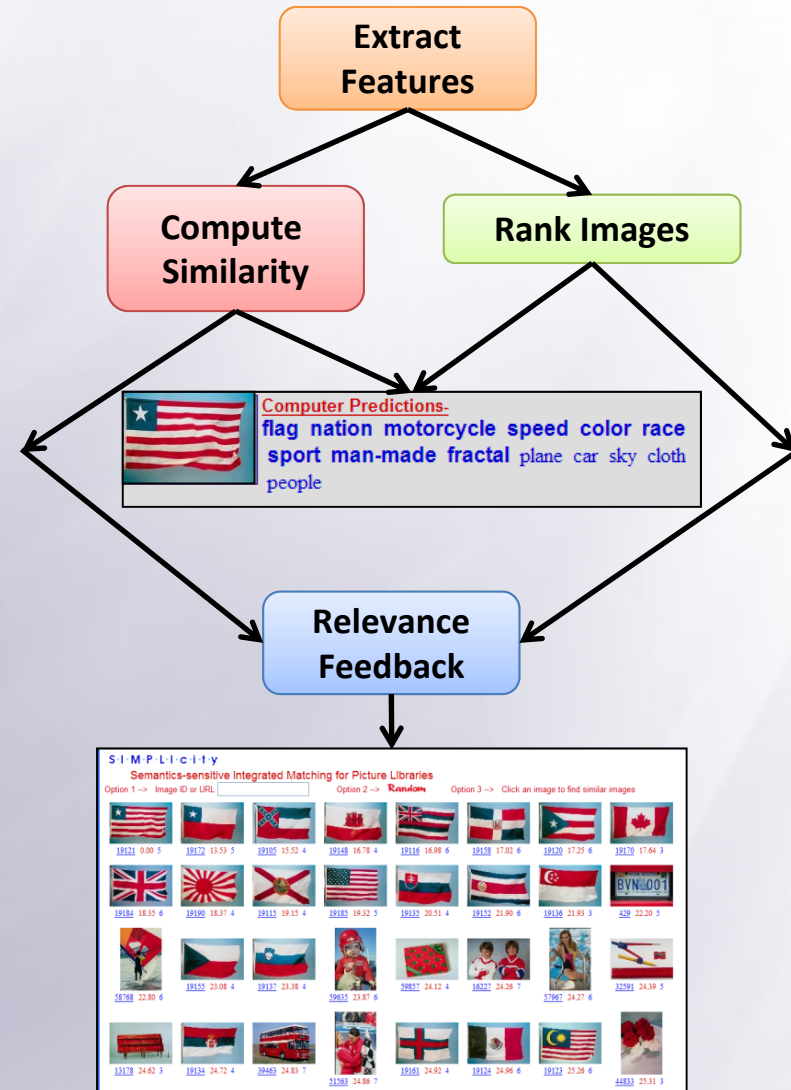
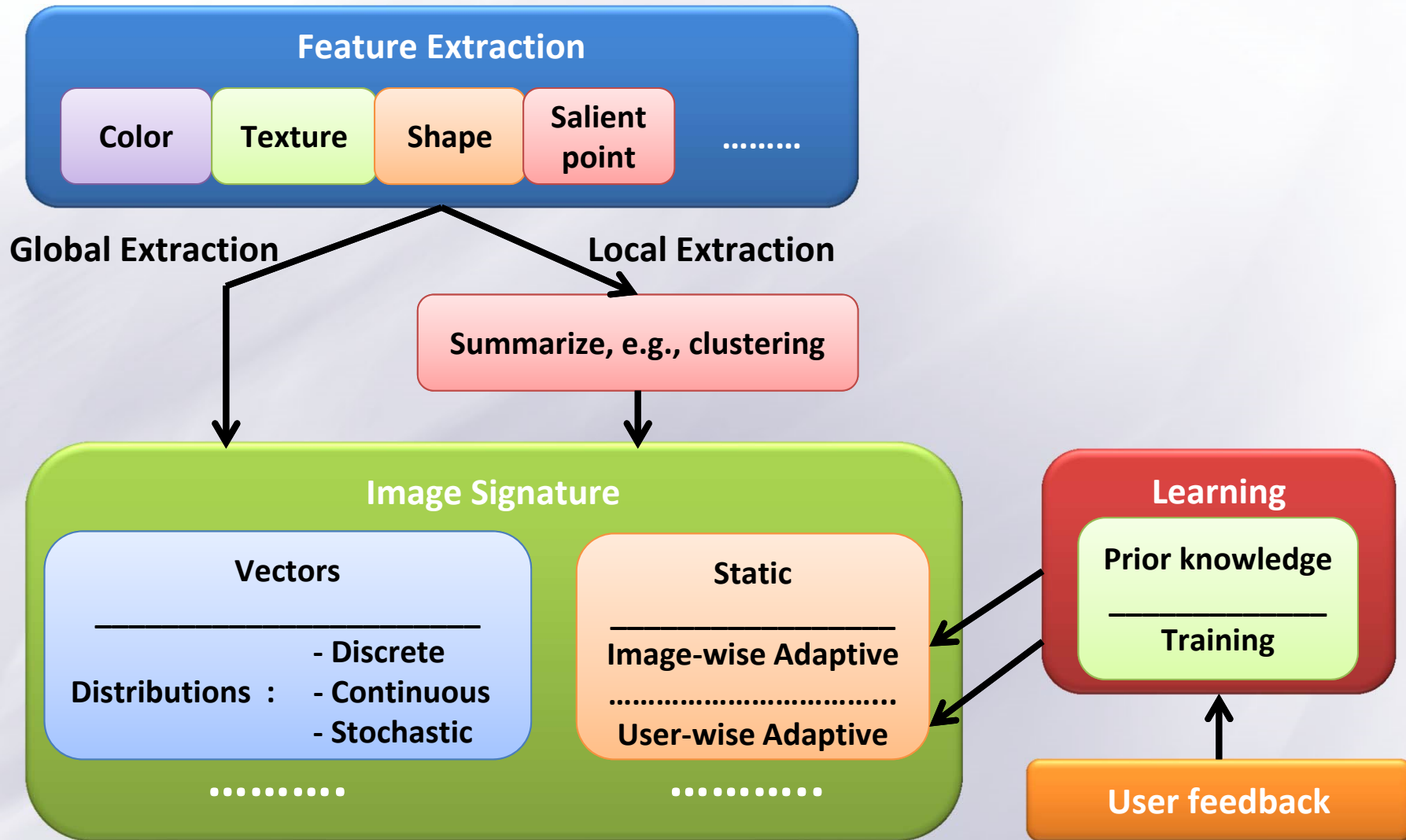


Image signature formulation

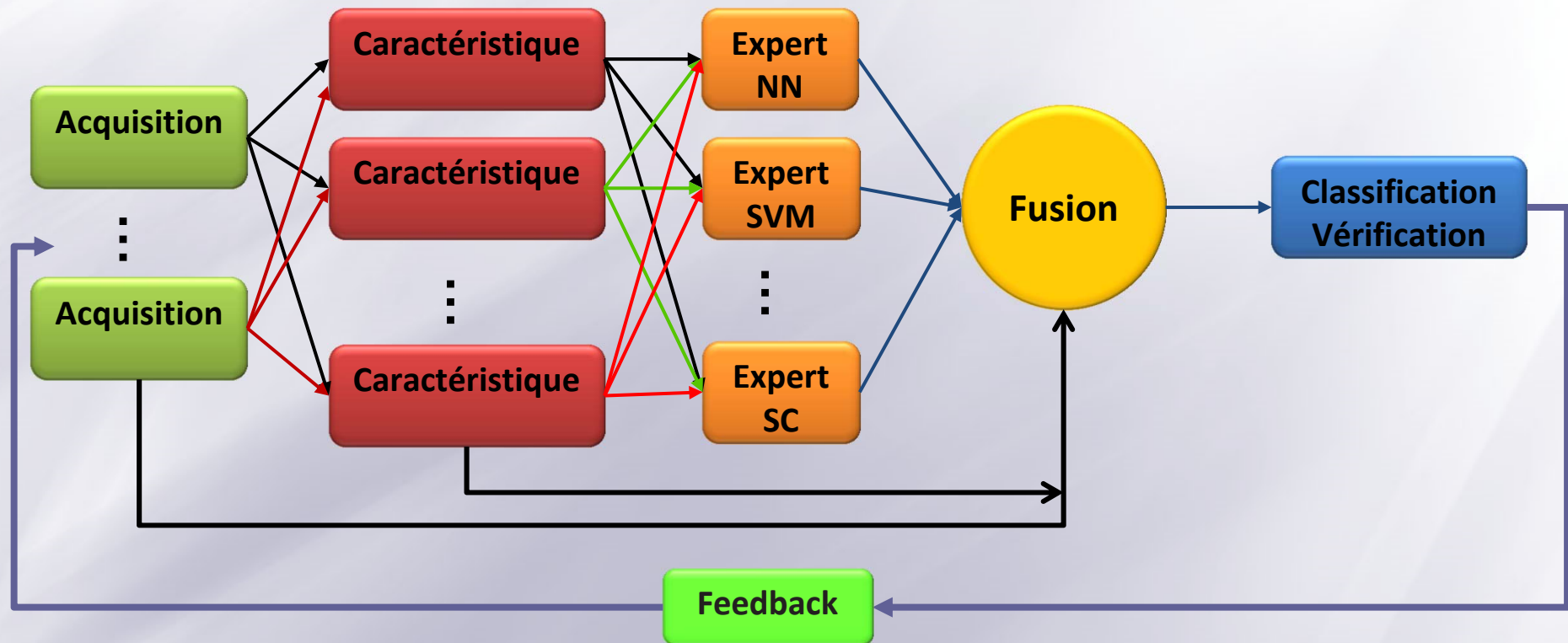


Query types

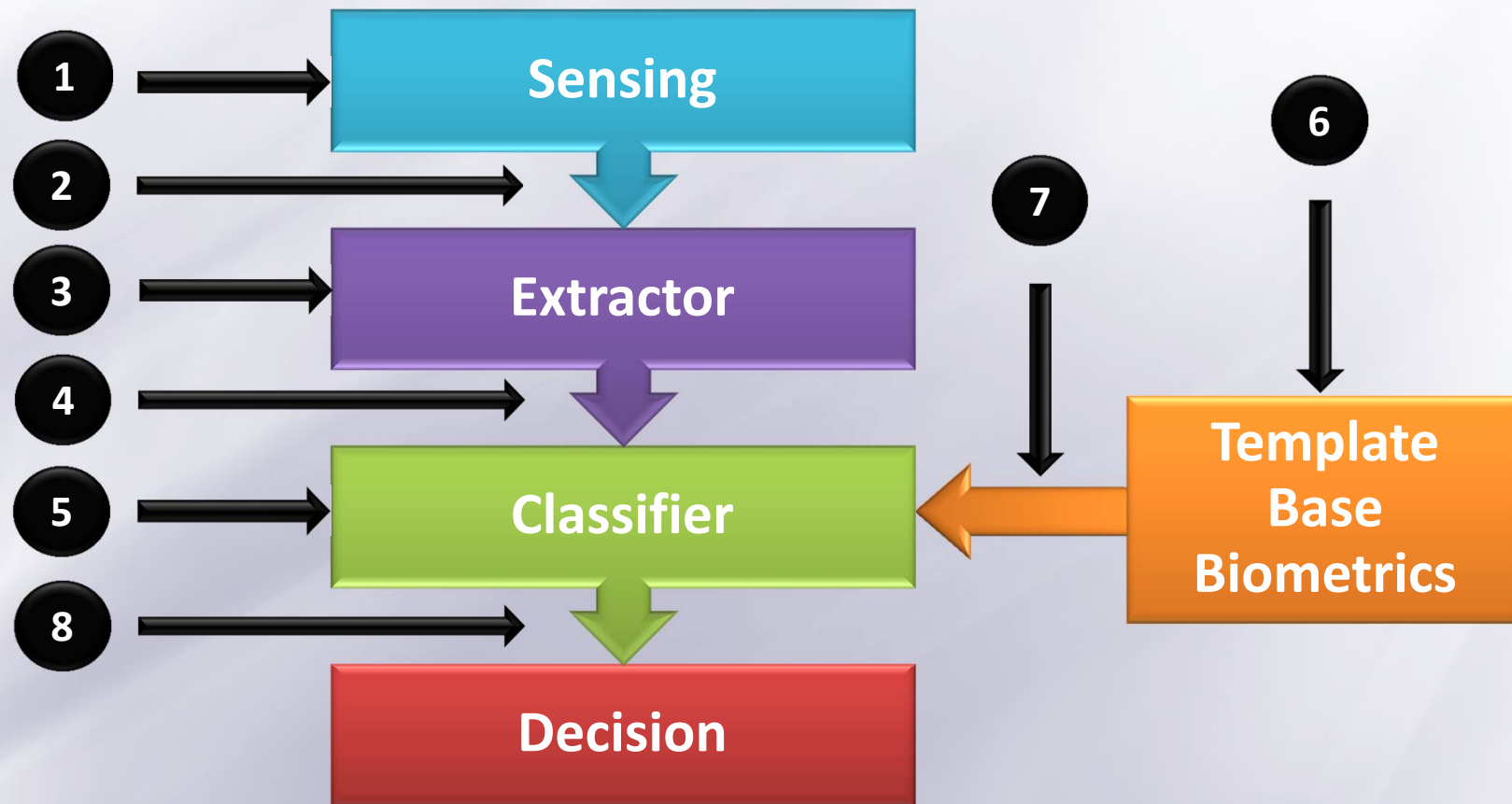
☰ Three levels of increasing complexity:

- **Level 1: Retrieval by *primitive* features** such as colour, texture, shape or the spatial location of image elements
- **Level 2: Retrieval by *derived* features** (sometimes known as *logical*), involving some degree of logical inference about the identity of the objects depicted in the image
 - Retrieval of objects of a given type (e.g. “find pictures of a double-decker bus”)
 - Retrieval of individual objects or persons (“find a picture of the Eiffel tower”)
- **Level 3: Retrieval by abstract attributes**, involving a significant amount of high-level reasoning about the meaning and purpose of the objects or scenes depicted
 - Retrieval of named events or types of activity (e.g. “find pictures of Scottish folk dancing”)
 - Retrieval of pictures with emotional or religious significance (“find a picture depicting suffering”)

Classification et reconnaissance : Paradigme et architecture générale

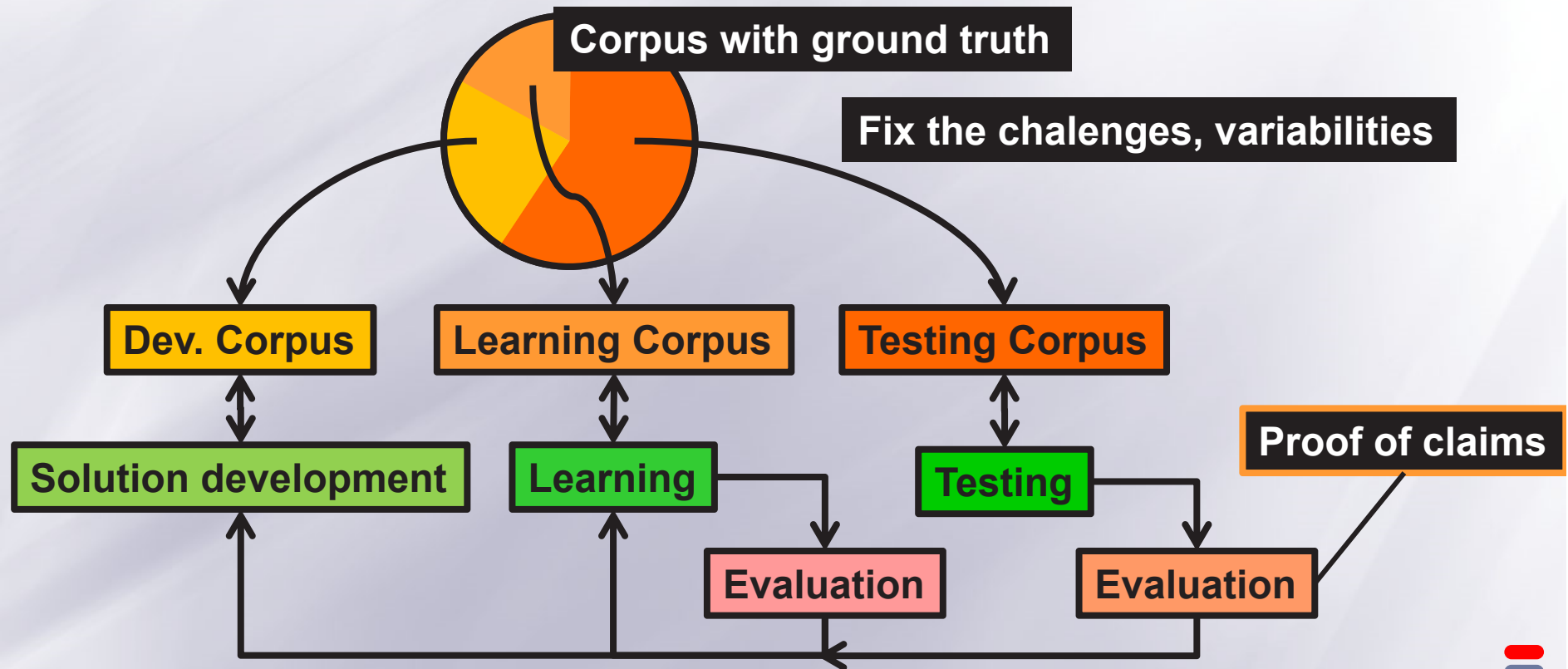


Biometrics Systems as a specific CBIR



Methodology for innovation

- Development of novel component: models, algorithms, features, classifiers, frameworks, etc.



What are the innovations ?

Modeling of the problem, the solution, and the assessment

- Emerging problem
 - Modeling
 - Solution
 - Assessment
- Existing problem
 - Novel modeling
 - Innovative new solution, new and improved solution
 - Assessment
- Dedicated dataset
- Assessment and Certification

Evaluation : protocole et facteurs mesurables

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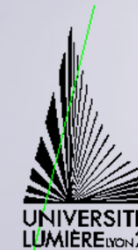
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Evaluation

☰ Corpus de développement, d'apprentissage et de test

- Evaluer une solution de manière objective
 - Représente le phénomène
 - Enferme des variabilités
 - Des objectifs précis sont visés : précision, robustesse, rapidité
- Comparer des solutions de manière objective

☰ Critères d'évaluation

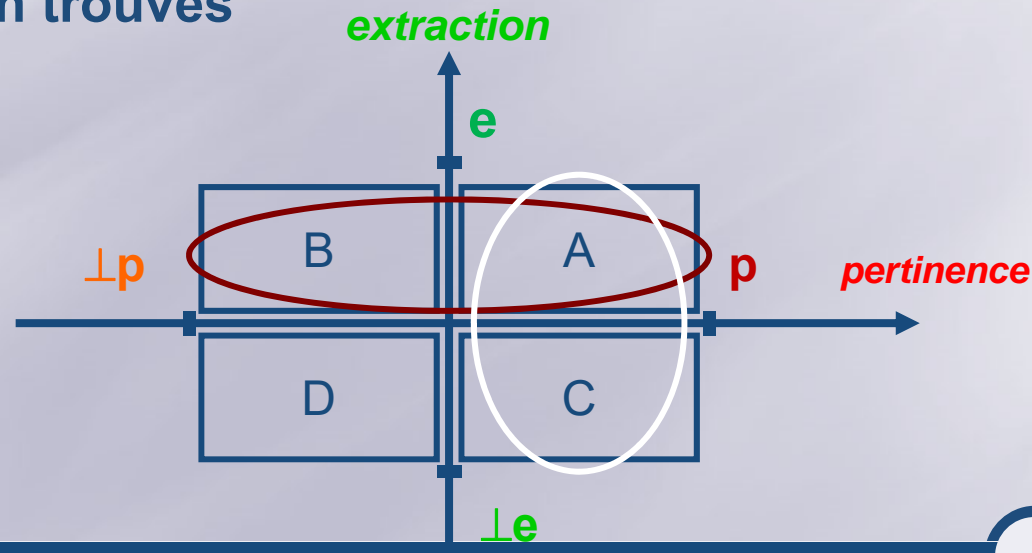
- Mesure d'efficacité
 - Taux de rappel, de précision, de bruit et de silence, etc.
- mais aussi, la précision quantitative, les complexités spatiale et temporelle

Comment mesurer ?

- Vrais positifs (*True Positive*) \Rightarrow A : Nb éléments pertinents trouvés
- Faux positifs (*False Positive*) \Rightarrow C : Nb éléments pertinents non trouvés
- Vrais négatifs (*True Negative*) \Rightarrow B : Nb éléments non pertinents trouvés
- Faux négatifs (*False Negative*) \Rightarrow D : Nb éléments non pertinents non trouvés

Méthode :

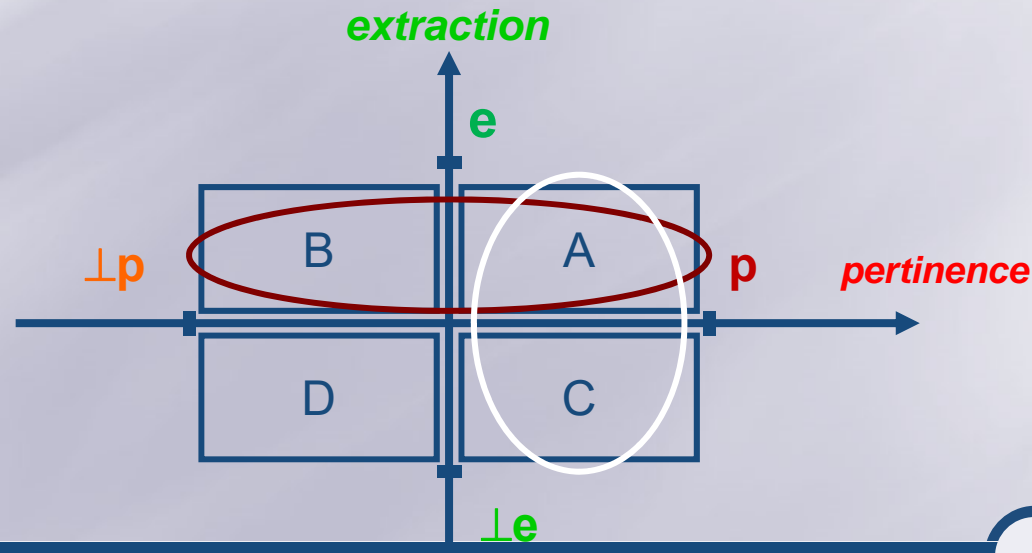
- Définition
- Visualisation
- Équation



Taux de précision (P)

La précision : elle mesure le taux d'éléments pertinents trouvés (classification, reconnaissance, segmentation) par rapport à l'ensemble d'éléments trouvés

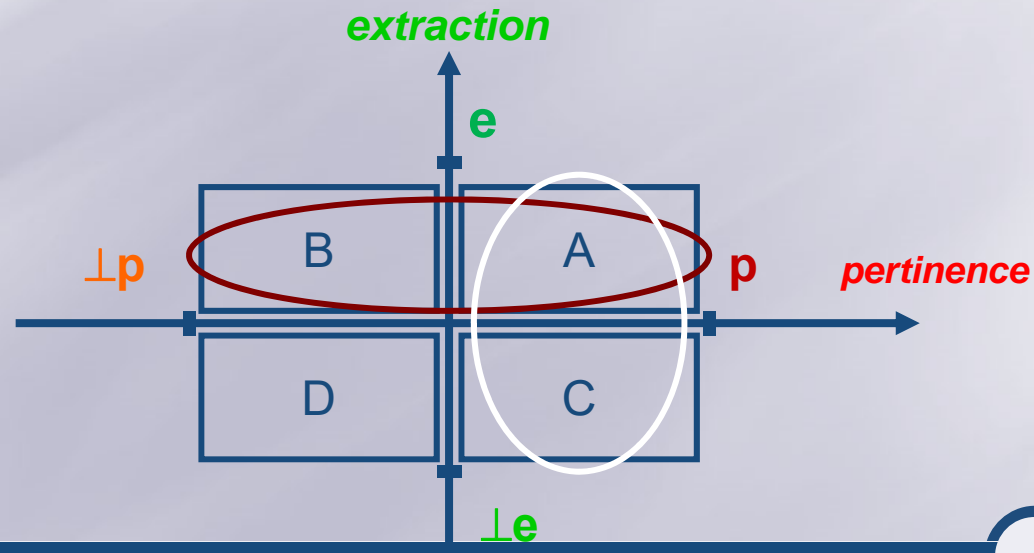
$$\text{Précision} = \frac{\text{nombre (éléments pertinents)}}{\text{nombre (éléments trouvés)}} = \frac{A}{A + B}$$



Taux de rappel

Le rappel : elle mesure le taux d'éléments pertinents trouvés (classification, reconnaissance, segmentation) par rapport à l'ensemble d'éléments pertinents existants dans le corpus

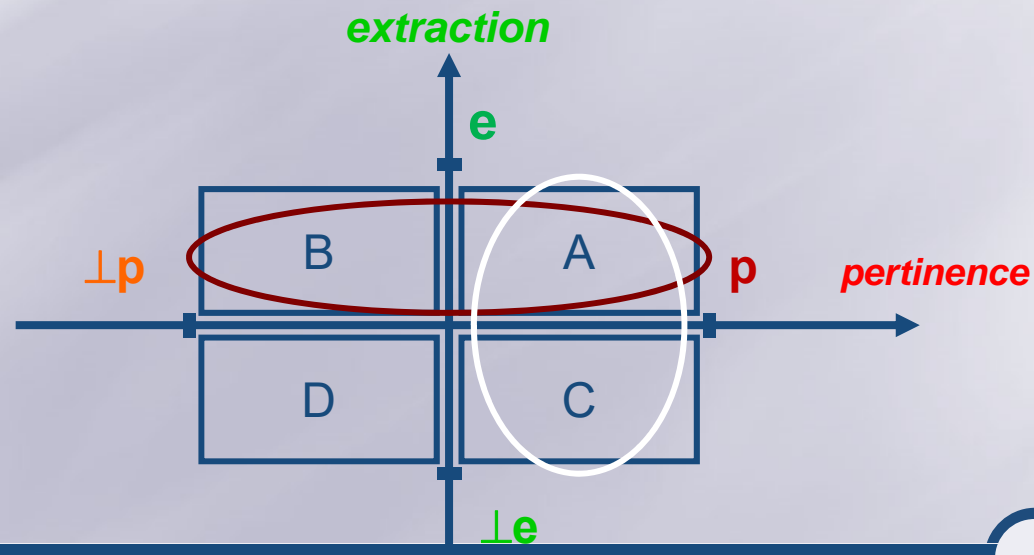
$$\text{Rappel} = \frac{\text{nombre (éléments pertinents trouvés)}}{\text{nombre (éléments pertinents dans le corpus)}} = \frac{A}{A + C}$$



Bruit

Le bruit : il mesure le taux d'éléments non pertinents trouvés par rapport à l'ensemble d'éléments trouvés

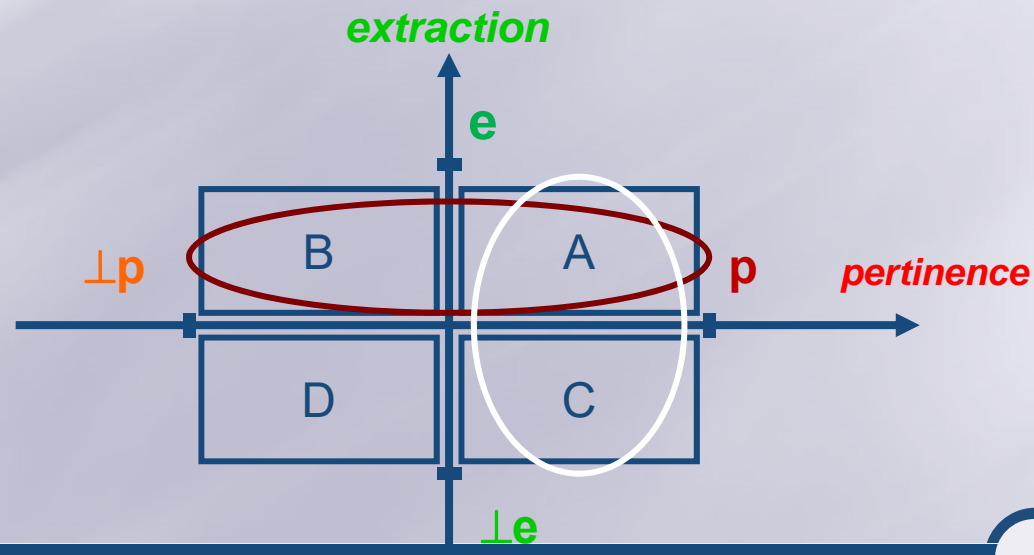
$$\text{Bruit} = \frac{\text{nombre (éléments non pertinents trouvés)}}{\text{nombre (éléments trouvés)}} = \frac{B}{A + B}$$



Silence

Le silence : il mesure le taux d'éléments pertinents non trouvés par rapport à l'ensemble d'éléments pertinents dans le corpus

$$\text{Silence} = \frac{\text{nombre (éléments pertinents non trouvés)}}{\text{nombre (éléments pertinents dans le corpus)}} = \frac{C}{A + C}$$



Terminology

- ☰ **True Positive (TP)**

eqv. with hit

- ☰ **True Negative (TN)**

eqv. with correct rejection

- ☰ **False Positive (FP)**

eqv. with false alarm, Type I error

- ☰ **False Negative (FN)**

eqv. with miss, Type II error

- ☰ **Sensitivity or True Positive Rate (TPR)**

eqv. with hit rate, Recall

$$TPR = TP/P = TP/(TP+FN)$$

- ☰ **False Positive Rate (FPR)**

eqv. With Fall-Out

$$FPR = FP/N = FP/(FP+TN)$$

- ☰ **Accuracy (ACC)**

$$ACC = (TP+TN)/(P+N)$$

- ☰ **Specificity (SPC) or True Negative Rate**

$$SPC = TN/N = TN/(FP+TN) = 1 - FPR$$

- ☰ **Positive Predictive Value (PPV)**

eqv. With Precision

$$PPV = TP/(TP+FP)$$

- ☰ **Negative Predictive Value (NPV)**

$$NPV = TN/(TN+FN)$$

- ☰ **False Discovery Rate (FDR)**

$$FDR = FP/(FP+TP)$$

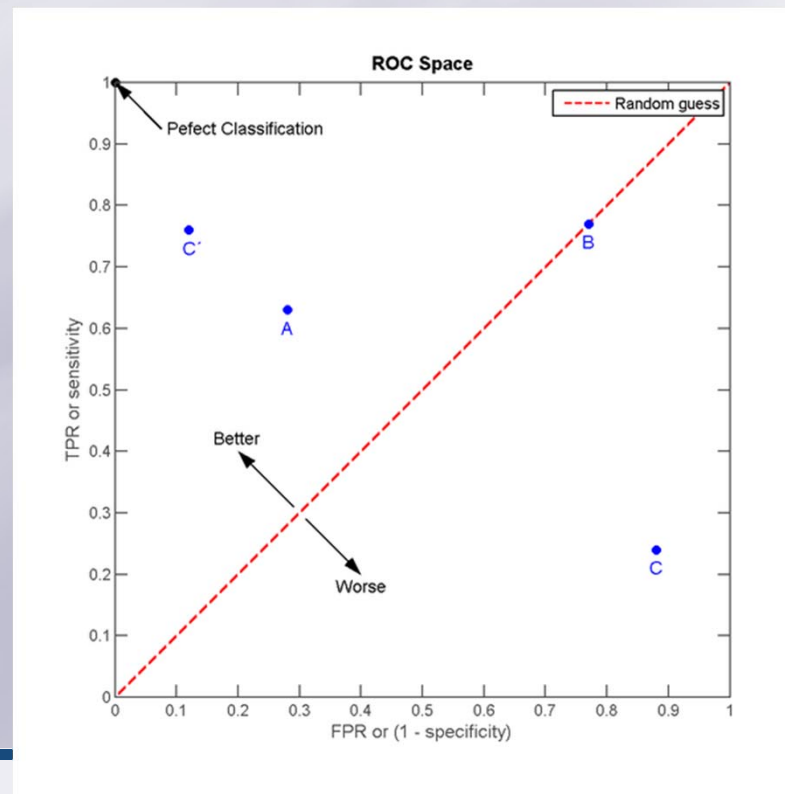
- ☰ **ROC**

- ☰ **DET**

- ☰ **Rank**

Courbe ROC - Receiver Operating Characteristic

- Le graphe des performances d'un système quand son seuil de discrimination varie. Obtenu en traçant $TPR = True Positive Rate$ en fonction de $FPR = False Positive Rate$ pour différentes valeurs de seuil.



Courbe DET - Detection Error Tradeoff

- Le graphe d'erreur d'un système. *FNR = False Negative Rate VS. FPR = False Positive Rate.*

