M1 Core course in computing for engineers

Exercise sheet 1 - Solving systems

- École Centrale de Lyon -

Exercise 1.

- 1. Create a 3×3 symmetric matrix A which has a 6 on its diagonal, a -4 on its second diagonal and a 1 at each corner.
- 2. Modify the gaussElimin function in order that it takes into account several constant vectors b.
- 3. Try your new function with matrix A and constant vectors

$$\begin{pmatrix} -14\\ 36\\ 6 \end{pmatrix} \text{ and } \begin{pmatrix} 22\\ -18\\ 7 \end{pmatrix}.$$

Exercise 2.

- 1. Write a function LUdecomp which takes a square matrix as argument and returns the decomposed matrix in Doolittle's procedure.
- 2. Write a function LUsolve which, from a LU Doolittle's decomposition matrix and a set of constant vectors stored in a matrix B, gives the set of solutions of LU = B.
- 3. Applied both functions in order to solve the system

$$\begin{cases} x_1 + 4x_2 + x_3 = 7\\ x_1 + 6x_2 - x_3 = 13\\ 2x_1 - x_2 + 2x_3 = 5. \end{cases}$$

Exercise 3. Choleski's decomposition can be found in both numpy.linalg and scipy.linalg. Find out the function, how to use it. Write a function Choleskisolve which solves, by using Choleski's decomposition, the system associated to the following data that you may copy-paste:

a = np.array([[1.44, -0.36, 5.52, 0.0], [-0.36, 10.33, -7.78, 0.0], [5.52, -7.78, 28.40, 9.0], [0.0, 0.0, 9.0, 61.0]])

b = np.array([0.04, -2.15, 0.0, 0.88])

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Exercise 4. Write an adaptation of the Doolittle's procedure to solve tridiagonal systems. Apply it to the system with coefficients

$$A = \begin{pmatrix} 6 & 2 & 0 & 0 & 0 \\ -1 & 7 & 2 & 0 & 0 \\ 0 & -2 & 8 & 2 & 0 \\ 0 & 0 & 3 & 7 & -2 \\ 0 & 0 & 0 & 3 & 5 \end{pmatrix}$$

and constants

$$b = \begin{pmatrix} 2\\ -3\\ 4\\ -3\\ 1 \end{pmatrix}$$

Exercise 5. Adapt the Doolittle procedure so that it can handle systems which should be pivoted, by using the swap of column described in the lecture. Apply it to

$$A = \begin{pmatrix} 0 & -1 & 1 \\ -1 & 2 & -1 \\ 2 & -1 & 0 \end{pmatrix} \quad b = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$